

Vector Balancing and Kernel Density Estimation

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Joint Work with Thomas Rothvoss

June 12, 2024



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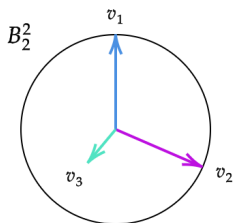
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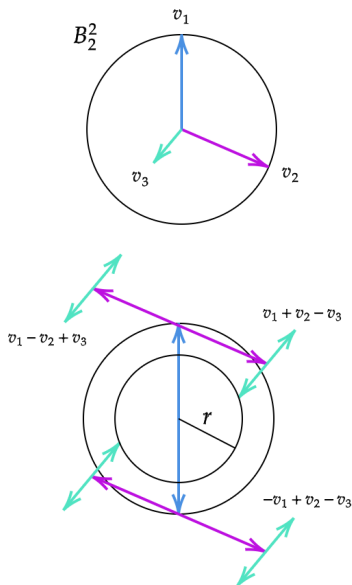
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Discrepancy Theory

$$\text{vb}(K, Q) := \sup \left\{ \min_{x \in \{\pm 1\}^n} \left\| \sum_{i=1}^n x_i v_i \right\|_Q : n \in \mathbb{N}, v_1, \dots, v_n \in K \right\}$$

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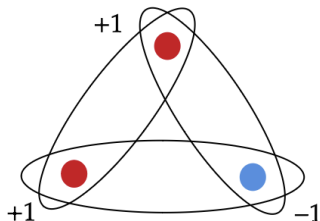
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Kernel Density Estimation

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Let ρ be a probability distribution on \mathcal{D} , $\{X_1, \dots, X_n\} \sim \rho$ i.i.d., and $\mathcal{K} : \mathcal{D} \times \mathcal{D} \rightarrow \mathbb{R}$. The *Kernel Density Estimator* (KDE) given by \mathcal{K} is then

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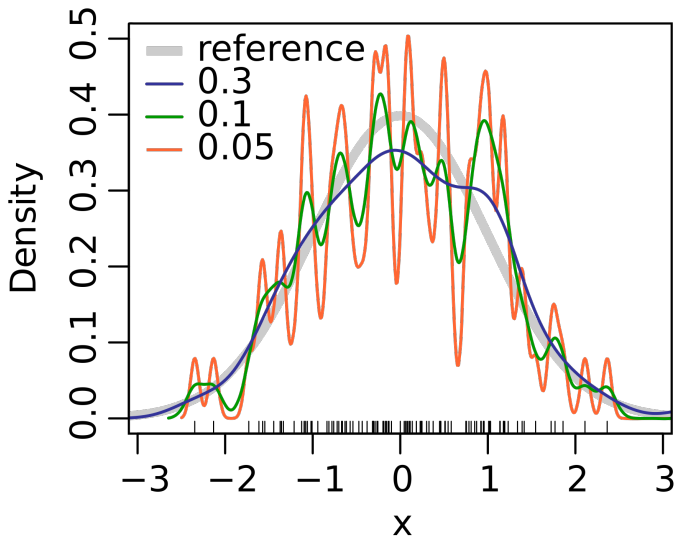
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- ▶ Well-known that $KDE_X(y)$ approximates ρ at the minimax optimal rate as $|X| \rightarrow \infty$ for "well-behaved" kernels

Kernel Density Estimation



Coresets for KDEs

Definition (ε -Coreset)

Given $\varepsilon > 0$, $K : \mathcal{D} \times \mathcal{D} \rightarrow \mathbb{R}$, and a data set $X \subseteq \mathcal{D}$, an ε -coreset for K is a subset $Q \subseteq X$ such that

$$\|\text{KDE}_X - \text{KDE}_Q\|_\infty = \sup_{y \in \mathcal{D}} \left| \frac{1}{|X|} \sum_{x \in X} K(x, y) - \frac{1}{|Q|} \sum_{q \in Q} K(q, y) \right| \leq \varepsilon.$$

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- ▶ The *coreset complexity* of a kernel function K is the minimum size coreset given any choice of $X \subseteq \mathcal{D}$
- ▶ Bounds depend on K and the dimension d of the data, and are independent of the size and choice of X .

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Suppose we can find **balanced** signs $\varepsilon \in \{\pm 1\}^n$ so that

$$\left\| \sum_{x \in X} \varepsilon_x K^x \right\|_{\infty} = \sup_{i \in [d]} \left| \sum_{x \in X} \varepsilon_x K(y_i, x) \right| \leq f(n, d).$$

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We take $S_- := \{x : \varepsilon_x = -1\}$ to be our coreset. For any $y \in \mathcal{D}$:

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Hope: $f(n, d)$ decays polynomially with n , get bound via iteration.

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And a related result...

- ▶ Karnin and Liberty, 2019: $\text{disc}(K) = O(\sqrt{d})$ under **very** strong assumptions on \mathcal{D}

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 - ▶ Significantly improved dependence on bandwidth parameter α for the exponential kernel

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Examples:

- ▶ Gaussian: $K_G(x, y) = \exp(-\alpha^2 \|x - y\|_2^2)$, $x, y \in \mathbb{R}^d$
- ▶ Laplacian: $K_L(x, y) = \exp(-\alpha \|x - y\|_2)$, $x, y \in \mathbb{R}^d$
- ▶ JS: $K_{JS}(x, y) = \exp\left(-\alpha\left(H\left(\frac{x+y}{2}\right) - \frac{H(x)+H(y)}{2}\right)\right)$, $x, y \in \Delta^d$

Key Theorem in Discrepancy Method

Theorem (Banaszczyk, '98)

Given any convex body $K \subseteq \mathbb{R}^m$ of Gaussian measure $\gamma_m(K) \geq 1/2$, and vector $v_1, \dots, v_n \in B_2^d$, there exist signs $\varepsilon \in \{\pm 1\}^n$ such that $\sum_{i \in [n]} \varepsilon_i v_i \in CK$, $C > 0$ an absolute constant.

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Theorem (Dadush et.al., 2018)

There is a polynomial-time randomized algorithm that takes as input vectors $v_1, \dots, v_n \in \mathbb{R}^m$ of ℓ_2 norm at most 1 and outputs random signs $\varepsilon \in \{\pm 1\}^n$ such that the (mean-zero) random variable $\sum_{i \in [n]} \varepsilon_i v_i$ is $O(1)$ -subgaussian.

Reproducing Kernel Hilbert Spaces

Theorem (Moore-Aronszajn, 1950)

Let T be a set and K a positive definite function on $T \times T$. Then there is a map $\phi : T \rightarrow \mathcal{H}_K$ to a unique corresponding reproducing kernel Hilbert space \mathcal{H}_K so that for any $s, t \in T$,

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- ▶ Dadush et. al $\implies \exists \varepsilon \in \{\pm 1\}^n$ such that $\sum_{x \in \mathcal{X}} \varepsilon_x \phi(x)$ is $O(1)$ -subgaussian.

Our Approach

Restated Goal: bound

$$\sup_{y \in Q} |\langle \Sigma, \phi(y) \rangle_{\mathcal{H}_K}| = \sup_{y \in Q} \left| \sum_{x \in X} K(x, y) \right|,$$

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Let $(X_t)_{t \in T}$ be a mean zero random process on a pseudometric space (T, d) satisfying $\|X_t - X_s\|_{\psi_2} \leq d(t, s)$ for all $t, s \in T$. Then

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Key Idea: Apply Dudley to $\Sigma_y := \langle \Sigma, \phi(y) \rangle$ for $y \in Q$ with d given by $\|\cdot\|_{\mathcal{H}_K}$, the *kernel distance*

Future Ideas

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- ▶ In general, we expect the bandwidth parameter to depend on n . If we account for this in our iteration, can we get better bounds?
- ▶ Can assumed properties of the distribution give us better bounds?

Thank You!

Questions? :)